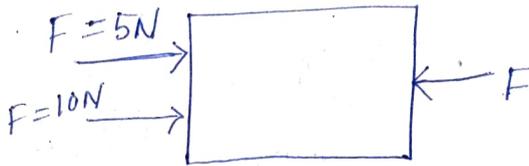


Scalar and vector

Physical quantity - The quantity which we can measure for that we need two things Magnitude and direction.

→ Some physical quantity have magnitude to represent but some physical quantity refers to both magnitude and direction.



here 5N or 10N represents a magnitude of physical quantity force

Physical quantity

Scalars

(Scalars only magnitude)

Mass, volume

density, time

Vectors

(magnitudes as well as direction)

Force, displacement

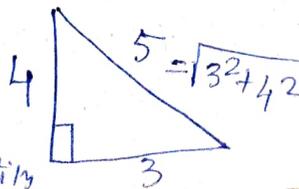
Velocity, acceleration

Scalar :- The physical quantity which can obey Algebraic Addition is known as scalar quantity.

Add :- $5\text{kg} + 3\text{kg} = 8\text{kg}$ (Algebraic Addⁿ)

Vector Addition

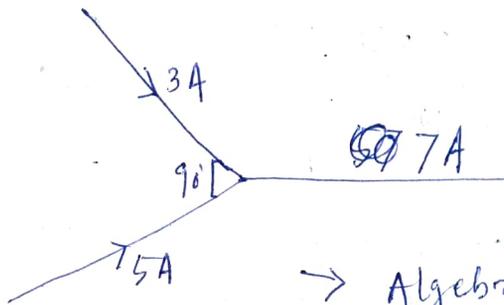
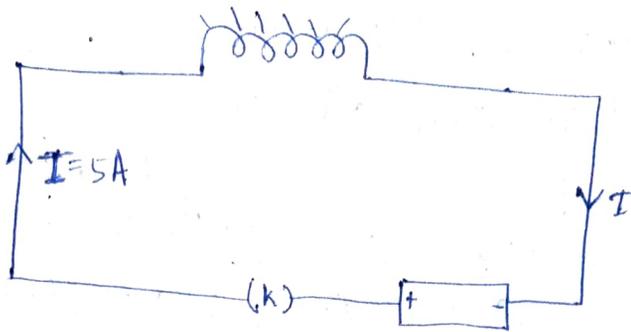
The physical quantity which can obey Geometric addition known as vector quantity



Magnitude :- Magnitude refers to a quantity or ~~direction~~ capacity or size. (e.g. - 3ms father sleep)

Ex Current

both magnitude and direction



→ Algebraic sum.

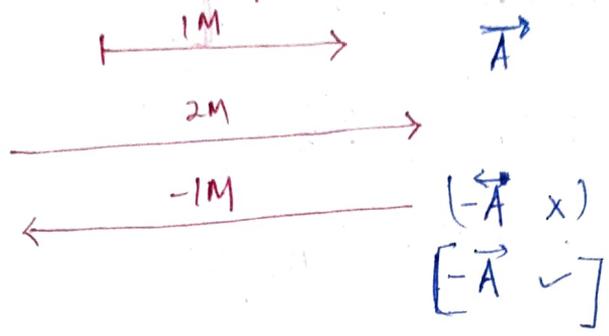
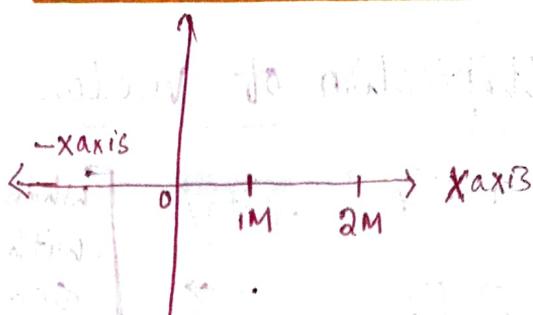
→ Current is that physical quantity which have both magnitude and direction but it obey Algebraic sum. So we called it Tensor.

Tensor :- It is a scalar quantity which has direction.

Ex - Current, Pressure

Graphical representation of a vector :-

- There is a sign to represent any physical quantity like $5^{\circ} \rightarrow$ temp. (vector \rightarrow) represents
- on vector (+ or -) represents their direction not their magnitude



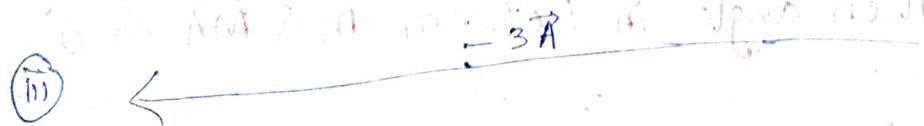
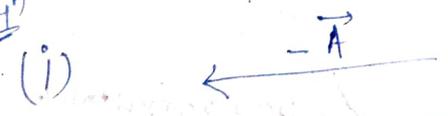
$A \rightarrow$ scalar quantity
 $\vec{A} \rightarrow$ vector quantity

Problem 1

Draw the graphical representation of following physical quantity.

- (i) $-\vec{A}$
- (ii) $+2\vec{A}$
- (iii) $-3\vec{A}$

Solⁿ



~~multiple~~

Multiplication of Vector with a Scalar

$$m(\vec{A}) = m\vec{A}$$

ex-1 $2(\vec{A}) = 2\vec{A}$

When scalar multiply with vector it gives scalar

② $-2(\vec{A}) = -2\vec{A}$

③ $0(\vec{A}) = 0 \cdot \vec{A} = 0$

EX-1

\vec{A} →

$m = +2$

When +ve scalar multiply with a vector then angle is 0°

$m(\vec{A}) = +2\vec{A}$

→

EX-2

$m = -2$

$m(\vec{A}) = -2\vec{A}$

←

When -ve scalar multiply with +ve vector then angle is 180°

Note

i) If $m = +ve$ scalar then angle in between m & $m\vec{A}$ is 0°

ii) If $m = -ve$ scalar then angle in between m & $m\vec{A}$ is 180°

Task

① If $m = +3$ then Draw $m\vec{A}$

② If $m = -3$ then draw $m\vec{A}$

Types of vector

(i) Zero vector / ~~Null~~ ^{Null} vector ($\vec{0}$)

(ii) Unit vector

(iii) orthogonal vector / Base vector

(iv) Equal vector

(v) Negative vector

(vi) Co-linear vector

(vii) Co-planar vector

(viii) Localised vector

(ix) Non-localised vector

(i) Zero vector ($\vec{0}$) :-

1) magnitude = 0

2) It has no specific direction

Properties :-

$$\textcircled{1} \vec{A} + \vec{0} = \vec{A}$$

(no change in magnitude & direction)

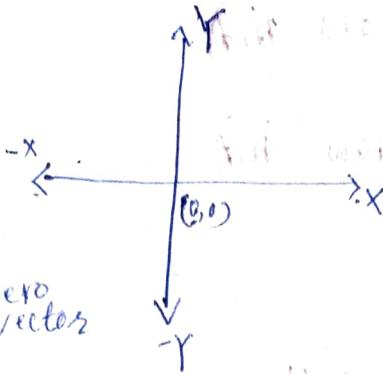
$$\textcircled{2} \vec{A} - \vec{0} = \vec{A}$$

$$\textcircled{3} \vec{A} \times \vec{0} = \vec{0}$$

$$\textcircled{4} \vec{A} \cdot \vec{0} = 0$$

$$\vec{A} - \vec{A} = \vec{0}$$

EX



arbitrary direction \rightarrow zero vectors

(ii) Unit vector :-

$$\vec{A} = A \hat{A}$$

\downarrow
magnitude

Let's a student ask of \vec{A} is a vector how to represent its magnitude & direction.

Though only magnitude means scalar we don't put cap over A.

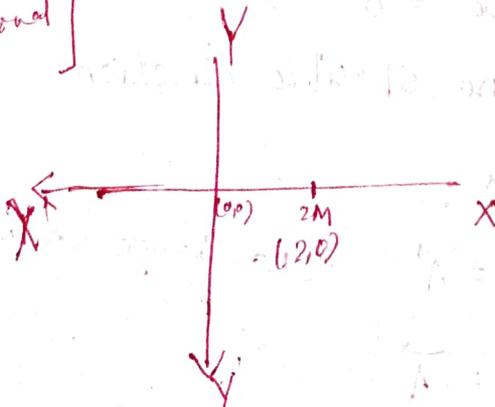
(i) \hat{A} is a unit vector whose magnitude = 1

(ii) Its direction is along the direction of its parent vector.

ex $\vec{B} = B \hat{B}$ (\hat{B} directed towards B)

ex $\vec{C} = C \hat{C}$

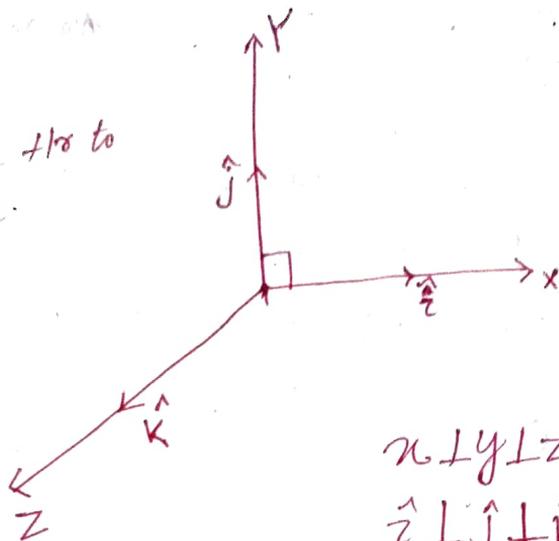
Question [Orthogonal vectors]



(iii)

Orthogonal vector / Base vector :-

x, y, z are \perp to each other.



$$x \perp y \perp z$$

$$\hat{i} \perp \hat{j} \perp \hat{k}$$

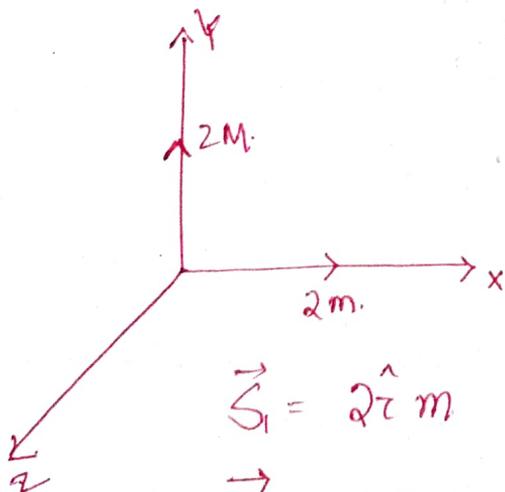
The unit vector which are \perp with each other is known as orthogonal vector.

ex- $\hat{i}, \hat{j}, \hat{k}$

→ All orthogonal vector bound to be unit vector

→ Unit vector could be orthogonal or not be orthogonal

EX



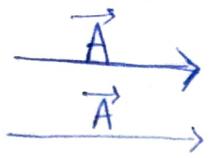
$$\vec{S}_1 = 2\hat{i} \text{ m}$$

$$\vec{S}_2 = 2\hat{j} \text{ m}$$

$$\vec{S}_3 = 2\hat{k} \text{ m}$$

$\vec{S} = -2\hat{i} \text{ m}$
magnitude = 2m
direction = $-\hat{x}$

iv) Equal vector :-



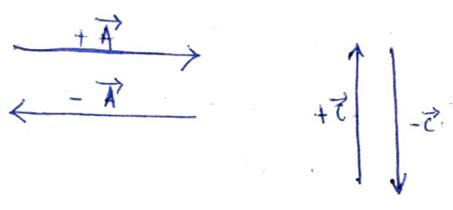
Length represent magnitude
 Arrow represent direction

vectors having same magnitude and same direction is known as Equal vector.

→ Angle betⁿ them is zero (0°)

$$+\vec{A} = +\vec{C}$$

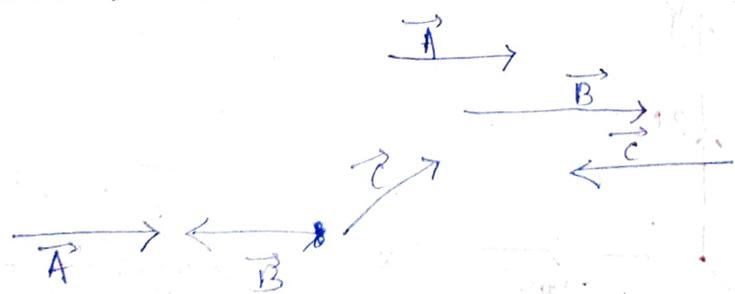
v) Negative vector :-



Same in magnitude but opposite in direction is known as Negative vector.

vi) Co linear vector :-

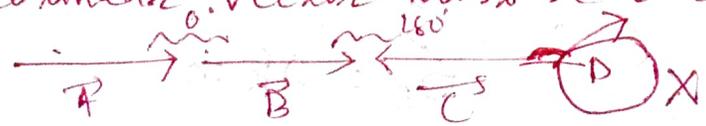
The vector having same line of action is called co-linear vector.



here \vec{A} & \vec{B} are co-linear but \vec{C} is not as the line of action of \vec{C} is not same.

here condition

→ For co-linear vector must be 0° or 180°



→ If the angle between two vectors is not 0° or 180° then it is called Non. co-linear vector

ex



Collinear vector



Parallel vector

Anti parallel vector

$$\theta = 0^\circ \text{ (Angle betⁿ vectors)}$$

$$\theta = 180^\circ$$

Magnitude may or may not be equal.

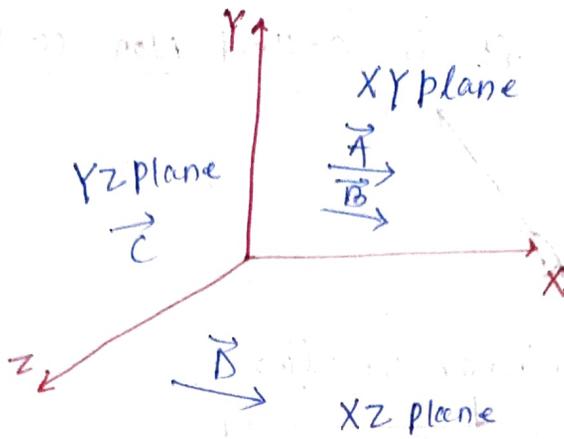
⊛ What is the difference between equal and parallel vectors ?

Ans In case of equal vectors magnitude ~~may~~ should be same. but in case of parallel magnitude may be or may not be same.

→ All equal vectors are parallel but may or may not be parallel vectors are equal.

→ In case of Anti parallel vector direction must be opposite magnitude may or may not be same but in case of ~~a~~ Negative vector magnitude must be same and direction must be opposite.

Vii) Coplaner vector



→ Here \vec{A} & \vec{B} are coplaner vector.

→ \vec{A} & \vec{C} or \vec{C} & \vec{D} can't be coplaner vector.

When two vectors lies on the same plane then it is said to be coplaner vector.

→ When ~~they are~~ vectors are not in same plane is called non-coplaner vector.

Viii) Localised vector

Vector whose initial point is fixed is known as localised vector.



Home task

Write mathematical vector form

① 2M along -x axis.

② 0.5m along z axis

Vector Addition

$$\vec{A} + \vec{B} = \vec{R}$$

(if we add two vector then the resultant must be a vector)

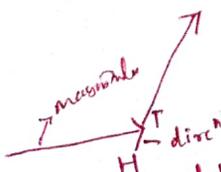
We have three methods for vector Addition.

- (i) Triangle's law of vector Addition
- (ii) Parallelogram law of vector Addition
- (iii) Polygons law of vector Addition

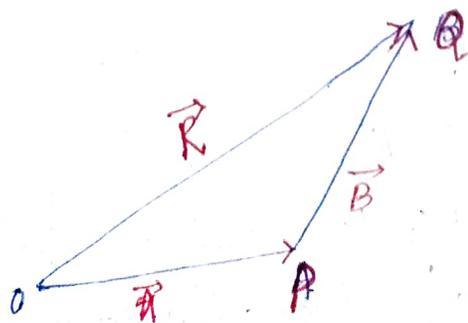
(i) Triangle's law

If two vectors are represented on the two sides of a triangle are taken in same order then their resultant vector must be represented on the third side of this triangle is taken in opposite order.

$$\vec{A} + \vec{B} = \vec{R}$$



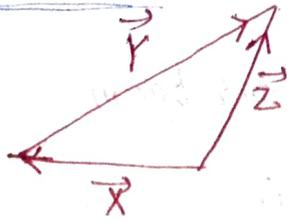
head-tail
tail-head } Same order



opposite order } Head-head

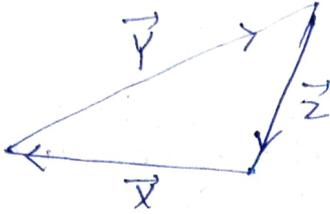
Graphical method

EX



$$\vec{Z} = \vec{X} + \vec{Y}$$

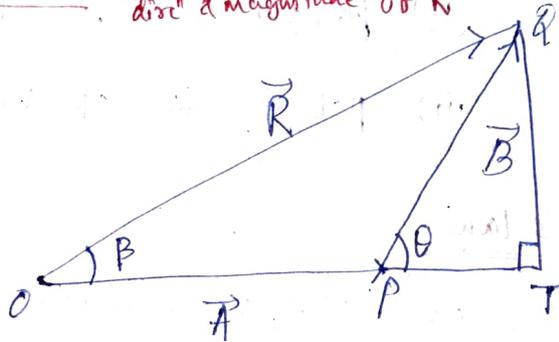
→ It is resultant vectors
 as \vec{Z} & \vec{Y} are opposite
 order but \vec{X} & \vec{Y} same order.



$$\vec{X} + \vec{Y} + \vec{Z} = 0 \quad \left(\text{Though their resultant vector is zero so it is a null vector} \right)$$

Analytical method

→ In analytical method we will find 'dir' & magnitude of \vec{R}



β = angle in between \vec{R} and \vec{A}

θ = angle in between \vec{A} and \vec{P}

[→ We will take angle between two vectors we want to add]

β → represents the direction of resultant vector \vec{R} .

From ΔOQT

$$\angle OTQ = 90^\circ$$

According to Pythagoras $[h^2 = b^2 + p^2]$

$$\Rightarrow OQ^2 = OP^2 + QT^2$$

$$\Rightarrow OQ^2 = (OP + PT)^2 + QT^2$$

as we are finding magnitude so i do not put ~~vector~~ over any term.

$$\Rightarrow OQ^2 = OP^2 + PT^2 + 2 \cdot OP \cdot PT + QT^2 \quad \text{--- (1)}$$

Note: In ΔPTQ if \angle and angle (θ) known then to find base we use $\cos \theta$
 to find perpendicular we use $\sin \theta$ we know

Consider ΔPQT

$$\cos \theta = \frac{B}{H} = \frac{PT}{PQ} = \frac{PT}{B}$$

$$\Rightarrow PT = B \cos \theta$$

$$\sin \theta = \frac{P}{H} = \frac{QT}{PQ} = \frac{QT}{B}$$

$$\Rightarrow QT = B \sin \theta$$

Putting the values of PT & QT in eqn (1)

$$\Rightarrow R^2 = A^2 + B^2 \cos^2 \theta + 2AB \cos \theta + B^2 \sin^2 \theta$$

$$\Rightarrow R^2 = A^2 + B^2 (\cos^2 \theta + \sin^2 \theta) + 2AB \cos \theta$$

$$\Rightarrow R^2 = A^2 + B^2 + 2AB \cos \theta$$

$$\Rightarrow R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$$

θ = Angle between \vec{A} & \vec{B} or two vectors.

→ Whenever it is asked find the ^{direction of} resultant vector then we have to find the value of β .

For direction of resultant vector

Consider $\Delta O T A$

$$\angle O T A = 90^\circ$$

$$\tan \beta = \frac{P}{B} = \frac{Q T}{O T} = \frac{Q T}{O P + P T}$$

$$\Rightarrow \tan \beta = \frac{B \sin \theta}{A + B \cos \theta}$$

→ I don't put vector sign over A & B. Because we can add, subtract multiply but we can't divide vector. So I haven't put it!

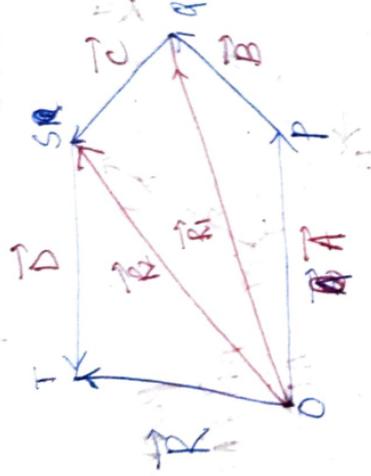
$$\Rightarrow \beta = \tan^{-1} \left[\frac{B \sin \theta}{A + B \cos \theta} \right]$$

β = direction of resultant vector.

iii) Polygon's law :-

Statement - If no. of vectors are acting simultaneously act at a point then the vectors are represented on the side of an open polygon are taken in same order then their resultant vector must be represented on the closing side of this polygon taken in opposite order.

$$\vec{A} + \vec{B} + \vec{C} + \vec{B} = \vec{R}$$



From ΔOPA

$$\vec{R}_1 = \vec{A} + \vec{B}$$

[As \vec{A} and \vec{B} are in same order but \vec{R}_1 in opposite order so it is a resultant vector.]

From ΔOQS

$$\vec{R}_2 = \vec{R}_1 + \vec{C}$$

$$\vec{R}_2 = (\vec{A} + \vec{B}) + \vec{C}$$

From ΔOST

$$\vec{R} = \vec{R}_2 + \vec{D}$$

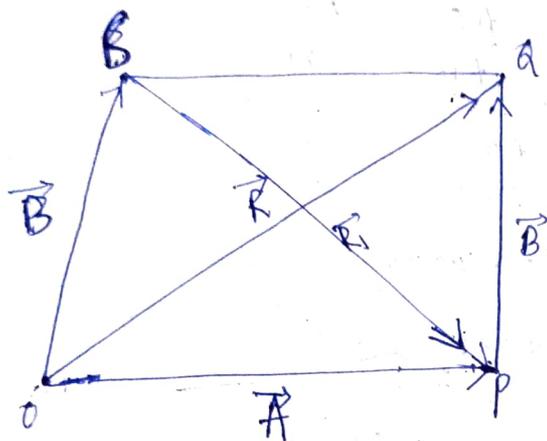
$$\Rightarrow \vec{R} = \vec{A} + \vec{B} + \vec{C} + \vec{D}$$

\rightarrow Polygon's law principle based upon triangles law

Parallelogram law of vector Addition:

Statement - If two vectors are represented on the two adjacent sides of a parallelogram drawn from a common point then their resultant vector must be drawn from that point and it represent on the diagonal of this parallelogram.

$$\text{i.e. } \vec{A} + \vec{B} = \vec{R}$$



From ΔOPA .

$$\vec{OA} = \vec{OP} + \vec{PA}$$

$$\vec{R} = \vec{A} + \vec{B}$$

ΔOSP

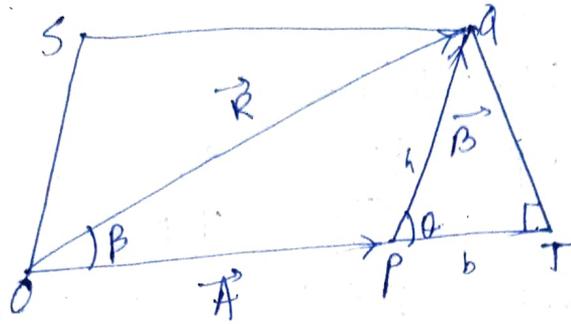
$$\vec{OP} = \vec{OS} + \vec{SP}$$

$$\Rightarrow \vec{A} = \vec{B} + \vec{R}_1$$

$$\Rightarrow \boxed{\vec{R}_1 = \vec{A} - \vec{B}}$$

\rightarrow In parallelogram law of vector addition if one diagonal is vector addition then another one must be the vector subtraction.

Analytical method: (we will find magnitude & direction)



[one perpendicular drawn]
 QT ~~is~~ from point A

From ΔOQT

$$OQ^2 = OT^2 + QT^2$$

$$OQ^2 = (OP + PT)^2 + QT^2$$

$$\Rightarrow OQ^2 = OP^2 + PT^2 + 2OPPT + QT^2$$

①
 → Not put here
 (i) find magnitude
 here

From ΔPQT

$$\angle PTQ = 90^\circ$$

$$\cos \theta = \frac{b}{h} = \frac{PT}{PQ} = \frac{PT}{B} \quad \left| \begin{array}{l} \sin \theta = \frac{P}{h} = \frac{QT}{PQ} = \frac{QT}{B} \\ \Rightarrow QT = B \sin \theta \end{array} \right.$$

$$\Rightarrow PT = B \cos \theta$$

Put all these values in equation (i) becomes

$$R^2 = A^2 + B^2 \cos^2 \theta + 2AB \cos \theta + B^2 \sin^2 \theta$$

$$\Rightarrow R^2 = A^2 + B^2 (\cos^2 \theta + \sin^2 \theta) + 2AB \cos \theta$$

$$\Rightarrow R^2 = A^2 + B^2 + 2AB \cos \theta$$

$$\Rightarrow R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$$

θ = angle between 2
 vectors

Now we will find direction

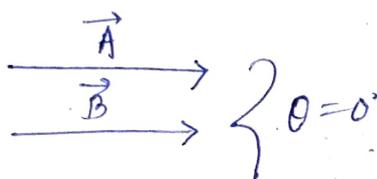
From ΔOQT ,

$$\angle OTQ = 90^\circ$$

$$\tan \beta = \frac{QT}{OT} = \frac{QT}{OP+PT}$$

$$\Rightarrow \tan \beta = \frac{B \sin \theta}{A + B \cos \theta}$$

Case-1 (Parallel vector)



Magnitude $R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$

Substituting $\theta = 0^\circ$ in the above eqn.
 $= \sqrt{A^2 + B^2 + 2AB}$

$$= \sqrt{(A+B)^2}$$

$$= A+B$$

Direction

$$\tan \beta = \frac{B \sin \theta}{A + B \cos \theta}$$

$$= \frac{B \sin 0^\circ}{A + B \cos 0^\circ}$$

$$= \frac{0}{A+B} = 0$$

$$\tan \beta = \tan 0^\circ$$

$$\beta = 0^\circ$$

\rightarrow In this case ~~magnitude~~ and direction is same as direction of two vectors

Case-2 (Anti-parallel vectors)



$$R = \sqrt{A^2 + B^2 + 2AB \cos 180^\circ}$$

$$= \sqrt{A^2 + B^2 - 2AB}$$

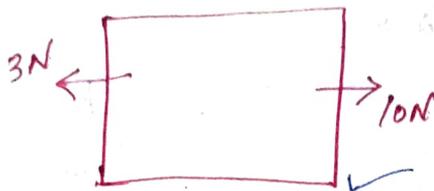
$$= \sqrt{(A-B)^2}$$

$$= A-B$$

→ In case of Antiparallel vectors we subtract both the magnitude. Direction is towards the vector having more/much magnitude.

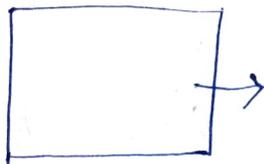
e.g

Find the net force.



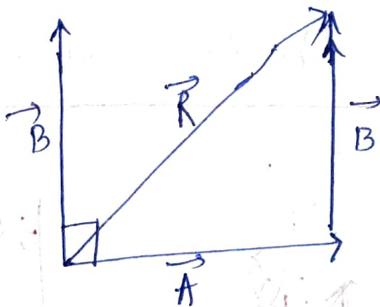
$$= 10\text{N} - 3\text{N}$$

$$= 7\text{N} (\because \text{directed towards } 10\text{N})$$



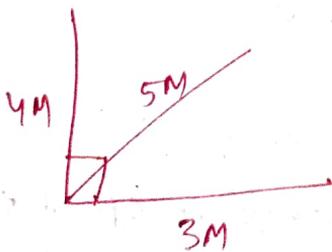
Case-3

Perpendicular vectors



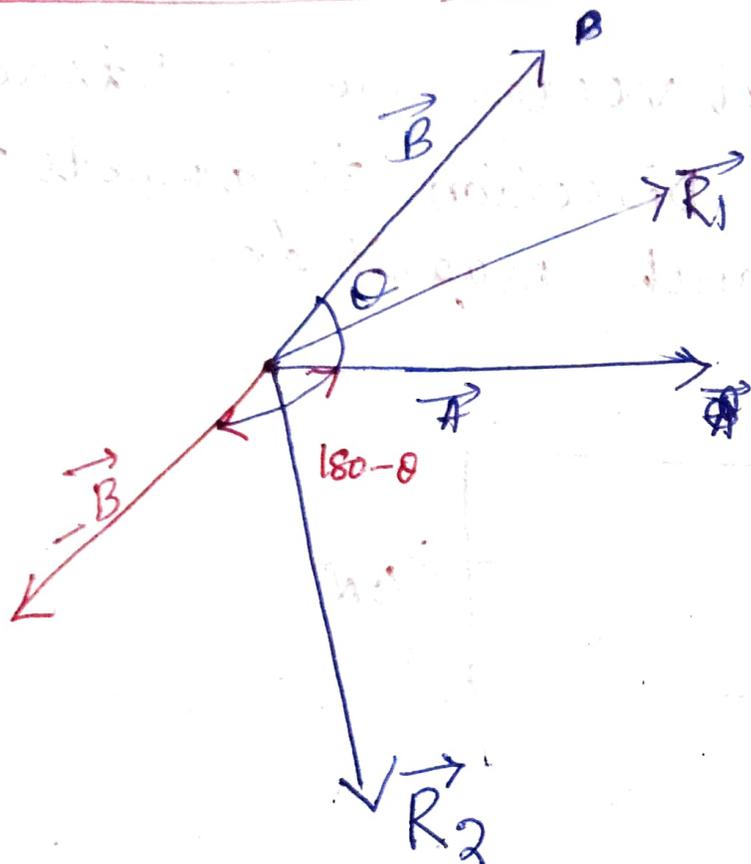
$$R = \sqrt{A^2 + B^2 + 2AB \cos 90^\circ}$$
$$= \sqrt{A^2 + B^2}$$

e.g



$$\sqrt{3^2 + 4^2} = 5$$

Vector Addition Subtraction



Here angle $= \theta$

$$\vec{R}_1 = \vec{A} + \vec{B}$$

$$R_1 = \sqrt{A^2 + B^2 + 2AB \cos \theta}$$

$$\vec{R}_2 = \vec{A} + (-\vec{B})$$

$$\Rightarrow \vec{R}_2 = \vec{A} - \vec{B}$$

Here Angle $(\theta) = 180 - \theta$

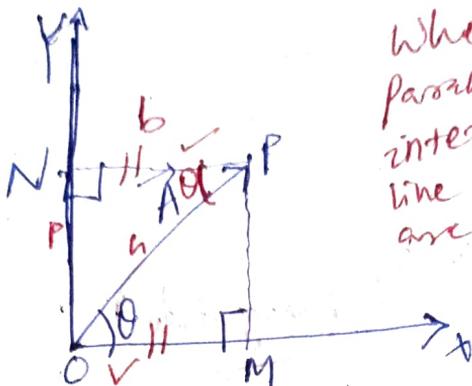
$$R_2 = \sqrt{A^2 + B^2 + 2AB \cos(180 - \theta)}$$

$$R_2 = \sqrt{A^2 + B^2 - 2AB \cos \theta}$$

$$\left[\begin{array}{l} \cos(180 - \theta) \\ = -\cos \theta \end{array} \right]$$

Resolution of a vector :-

Splitting of a vector is called resolution of a vector



Whenever two parallel lines are intersected by third line the opposite angles are equal

in ΔOMP

$$\cos \theta = \frac{b}{h} = \frac{OM}{OP} = \frac{OM}{A}$$

Sign not given over vector because we can't divide vector

$$\Rightarrow \boxed{OM = A \cos \theta}$$

(For x-axis - $\cos \theta$)

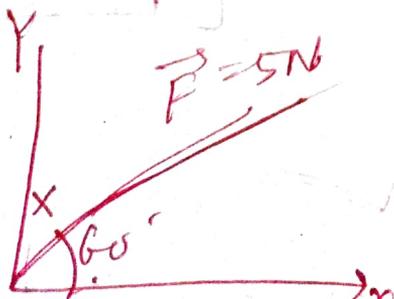
in ΔOPN

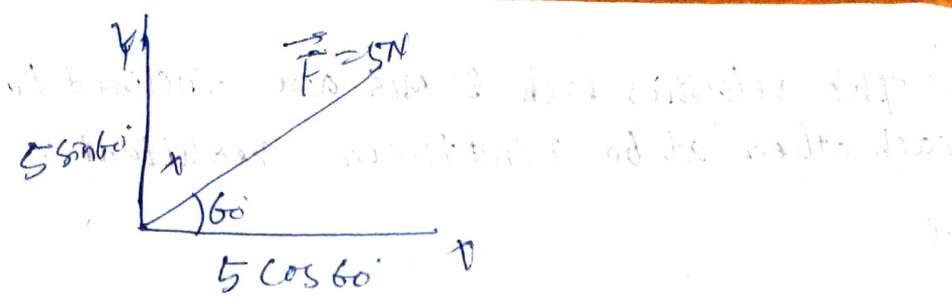
$$\sin \theta = \frac{p}{h} = \frac{ON}{OP} = \frac{ON}{A}$$

$$\Rightarrow \boxed{ON = A \sin \theta} \quad \text{(For y-axis } \sin \theta)$$

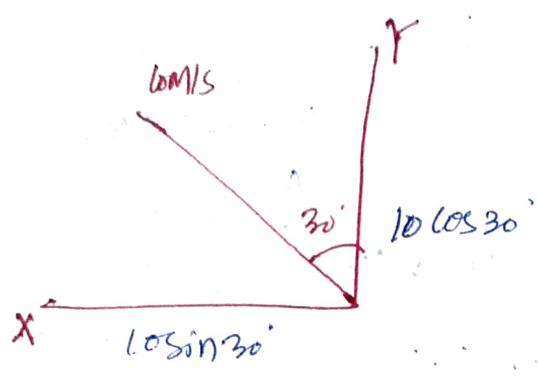
$A \cos \theta$ & $A \sin \theta$ are two components of A
rectangular component

example





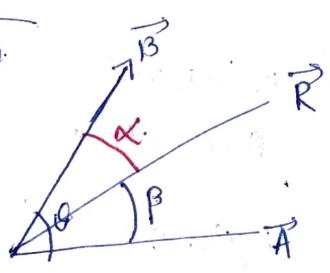
ex



Formula required for problems on scalar & vector

① $\vec{R} = \vec{A} + \vec{B}$

$R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$



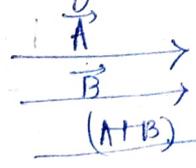
$\beta \rightarrow$ direction indicates

$\tan \beta = \frac{B \sin \theta}{A + B \cos \theta}$

Suppose angle α taken then

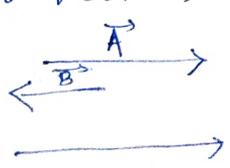
$\tan \alpha = \frac{A \sin \theta}{B + A \cos \theta}$

② From parallelogram law of vector addition



Resultant (magnitude of two vector)

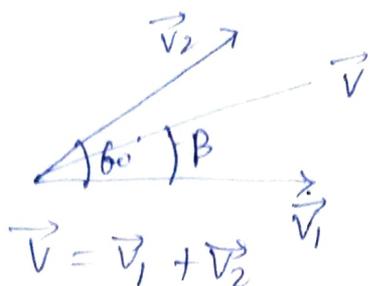
9) Antiparallel vectors



9) Antiparallel vectors ^{two vectors subtract} resultant to get resultant and direction towards the vector having more magnitude

Q-1 Two velocities each 5 m/s are inclined to each other at 60° . Find their resultant.

Sol



$$V_1 = V_2 = 5 \text{ m/s}$$
$$\theta = 60^\circ$$

Magnitude $V = \sqrt{V_1^2 + V_2^2 + 2V_1V_2 \cos \theta}$

$$= \sqrt{5^2 + 5^2 + 2 \cdot 5 \cdot 5 \cdot \cos 60}$$

$$= \sqrt{5^2 + 5^2 + 2 \cdot 5^2 \cdot \frac{1}{2}}$$

$$= \sqrt{3 \times 5^2}$$

$$= 5\sqrt{3} \text{ m/s}$$

$$= 5 \times 1.732$$

$$= 8.660 \text{ m/s}$$

direction $\tan \beta = \frac{V_2 \sin \theta}{V_1 + V_2 \cos \theta} = \frac{5 \sin 60^\circ}{5 + 5 \cos 60^\circ}$

$$= \frac{4 (\sin 60^\circ)}{8 (1 + \cos 60^\circ)}$$

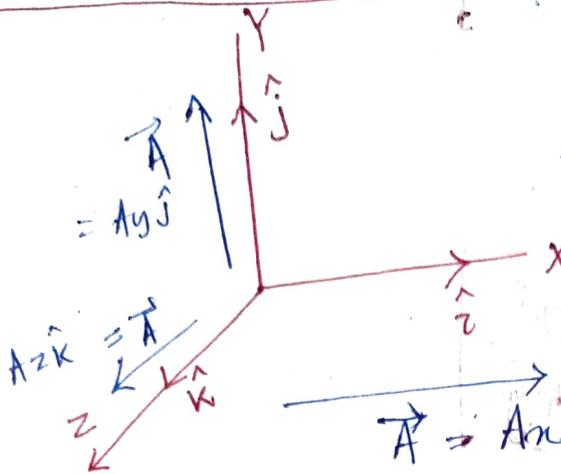
$$= \frac{\sin 60^\circ}{1 + \cos 60^\circ}$$

$$\tan \beta = \frac{\frac{\sqrt{3}}{2}}{1 + \frac{1}{2}} = \frac{\frac{\sqrt{3}}{2}}{\left(\frac{3}{2}\right)} = \frac{\sqrt{3}}{2} \times \frac{2}{3} = \frac{\sqrt{3}}{3} = \frac{1}{\sqrt{3}}$$

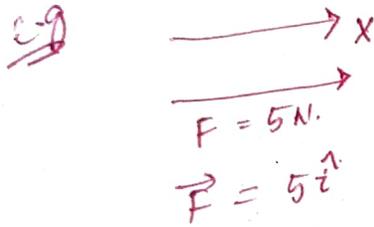
$$\Rightarrow \tan \beta = \tan 30^\circ$$

$$\boxed{\beta = 30^\circ}$$

Vector in one dimension.

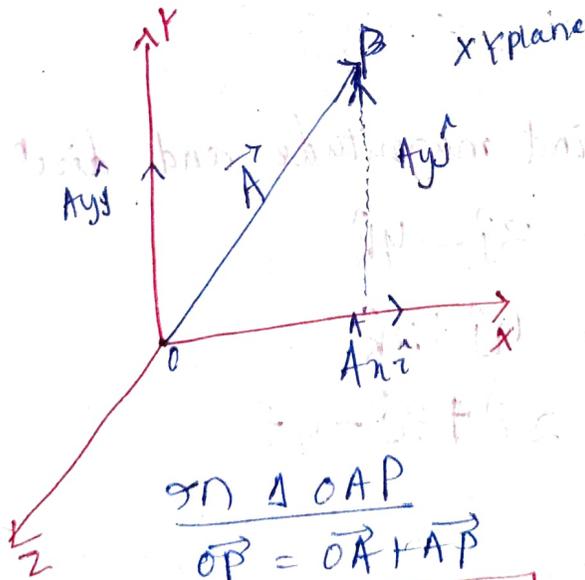


A vector is said to be one dimensional vector if it is parallel with any one of axis of a three co-ordinate axis.



Vector in two dimension

A vector is said to be two dimensional vector if it is lying in a two dimensional plane.



$$\text{In } \triangle OAP$$

$$\vec{OP} = \vec{OA} + \vec{AP}$$

$$\Rightarrow \boxed{\vec{A} = A_x \hat{i} + A_y \hat{j}}$$

here \vec{A} having two unit vectors \hat{i} & \hat{j} so it is said to be two dimensional.

$$|\vec{A}| = A = \sqrt{A_x^2 + A_y^2}$$

$$\vec{A} = A \hat{A}$$

$$\Rightarrow \hat{A} = \frac{\vec{A}}{A}$$

$$\Rightarrow \hat{A} = \frac{A_x \hat{i} + A_y \hat{j}}{\sqrt{A_x^2 + A_y^2}}$$

e.g $\vec{A} = 3\hat{i} + 4\hat{j}$

Find its magnitude and direction

Soln

$$|\vec{A}| = \sqrt{3^2 + 4^2} = \sqrt{25} = 5$$

$$\hat{A} = \frac{3\hat{i} + 4\hat{j}}{5}$$

$$\hat{A} = \left(\frac{3}{5}\right)\hat{i} + \frac{4}{5}\hat{j}$$

HW
Question

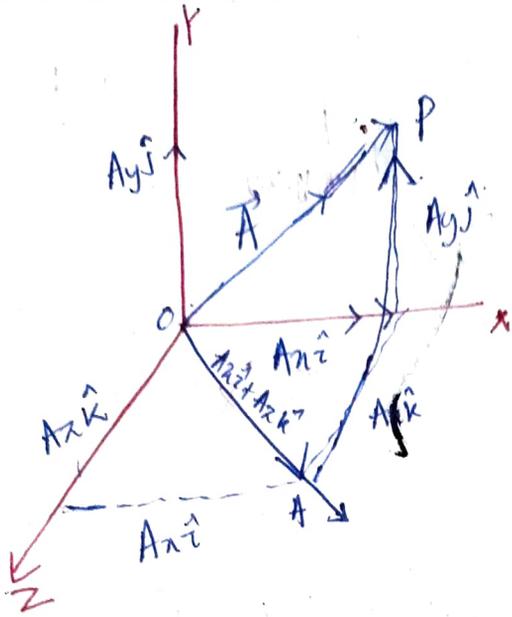
Find magnitude and dirⁿ of following vectors

① $\vec{A} = 3\hat{j} - 4\hat{k}$

② $\vec{B} = 4\hat{i} + 2\hat{k}$

③ $\vec{C} = 2\hat{i} + 3\hat{j} - 4\hat{k}$

Vector in three dimension



The TV we are watching is 2d but it has a x-axis & y-axis but on the other ^{waves} it comes forward towards us like x-y-z both are perpendicular to each other.

gn ΔOAP

$$\vec{OP} = \vec{OA} + \vec{AP}$$

brnd $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

magnitude

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

$$\hat{A} = \frac{\vec{A}}{A} = \frac{A_x \hat{i} + A_y \hat{j} + A_z \hat{k}}{\sqrt{A_x^2 + A_y^2 + A_z^2}}$$

direction

Ex 8.10
 $\vec{A} = 3\hat{i} - 4\hat{j} + 5\hat{k}$
 find $|\vec{A}|, \hat{A}$

Solⁿ

$$|\vec{A}| = \sqrt{3^2 + (-4)^2 + (5)^2} = \sqrt{50} = 5\sqrt{2}$$

$$\hat{A} = \frac{3\hat{i} - 4\hat{j} + 5\hat{k}}{5\sqrt{2}}$$

Vector Product : (subdivided into 2 sub-categories)

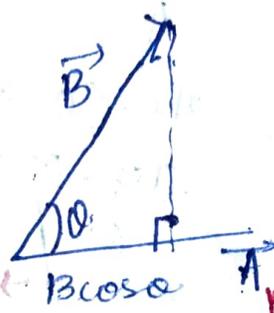
(1) Dot product or Scalar product

(2) cross product or vector product

(1) Dot product :-

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$= A(\underbrace{B \cos \theta}_{\text{magnitude}})$$



A's magnitude

$B \cos \theta$ (B's component)

→ As the result of dot product of two vectors is a scalar quantity so it is named as scalar product.

EX - $W = \vec{F} \cdot \vec{S}$

Work = Force x displacement

Work is a scalar because it obeys dot product

Ex Power = Force . velocity

$$P = \vec{F} \cdot \vec{v}$$

Properties of dot product ∴

(i) $\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$ (commutative)

(ii) $\vec{A} \cdot (\vec{B} + \vec{C}) = (\vec{A} \cdot \vec{B}) + (\vec{A} \cdot \vec{C})$ (distributive)

Ex

$$\vec{A} \cdot (\vec{B} \cdot \vec{C})$$

$$= \vec{A} \cdot \text{Scalar}$$

vector (can't write this expression)

Here dot product of two vectors gives the scalar

→ We can't do dot product of vector with scalar. For that dot product we need two vectors.

Characteristics of dot product :

1) Perpendicular vectors ($\theta = 90^\circ$)



$$\begin{aligned} \vec{A} \cdot \vec{B} &= AB \cos \theta \\ &= AB \cos 90^\circ \end{aligned}$$

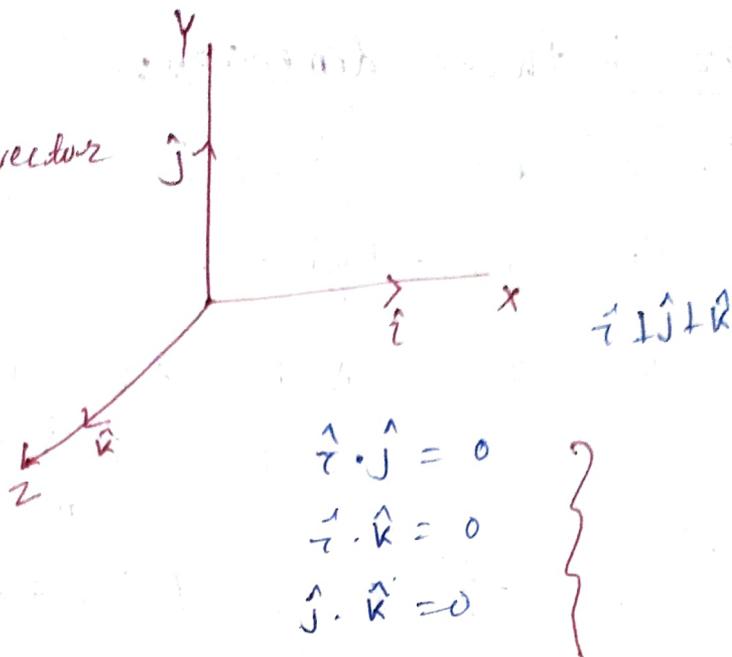
$$\boxed{\vec{A} \cdot \vec{B} = 0}$$

→ condⁿ for perpendicularity

→ If the dot product between two vectors is zero (0) then the angle between two vectors ($\theta = 90^\circ$).

For example

orthogonal vectors
we learnt



② Equal vector ($\theta = 0$)

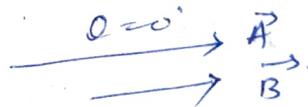
$$\begin{aligned}\vec{A} \cdot \vec{A} &= AA \cos \theta \\ &= A^2 \cos 0 \\ &= A^2\end{aligned}$$

$$\begin{aligned}\hat{i} \cdot \hat{i} &= |\hat{i}|^2 = 1^2 = 1 \\ \hat{j} \cdot \hat{j} &= 1 \\ \hat{k} \cdot \hat{k} &= 1\end{aligned}$$

Condⁿ for colinearity

③ colinear vectors

$$\begin{aligned}\vec{A} \cdot \vec{B} &= AB \cos \theta \\ &= AB \cos 0 \\ &= AB\end{aligned}$$



④ Vectors in three dimension:-

$$\text{Let } \vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\text{We know that } \vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{AB}$$

$$\Rightarrow \cos \theta = \frac{A_x B_x + A_y B_y + A_z B_z}{\sqrt{A_x^2 + A_y^2 + A_z^2} \cdot \sqrt{B_x^2 + B_y^2 + B_z^2}}$$

ex $\vec{A} = 2\hat{i} + 3\hat{j} - 4\hat{k}$

$$\vec{B} = \hat{i} + 2\hat{j} + 3\hat{k}$$

Find angle in between two vectors

$$\cos \theta = \frac{2+6-12}{\sqrt{4+9+16} \sqrt{1+4+9}}$$

$$\Rightarrow \cos \theta = \frac{-4}{\sqrt{29} \sqrt{14}}$$

$$\Rightarrow \cos \theta = \frac{-4}{\sqrt{391}} \Rightarrow \theta = \cos^{-1} \left(\frac{-4}{\sqrt{391}} \right)$$

Problems on dot product

Q1 $\vec{A} = 2\hat{i} + 3\hat{j} - \alpha\hat{k}$

$$\vec{B} = \alpha\hat{i} + 2\hat{j} - 3\hat{k}$$

For what value of α the two vectors are perpendicular with each other.

Sol For perpendicular $\vec{A} \cdot \vec{B} = 0$

$$\Rightarrow 2\alpha + 6 + 3\alpha = 0$$

$$\Rightarrow 5\alpha = -6$$

$$\Rightarrow \alpha = -\frac{6}{5}$$

$$\boxed{\alpha = -1.2}$$

Q2 Find Angle θ between two vectors
 $(\hat{i} + \hat{j})$ and $(\hat{i} - \hat{j})$

Sol

$$\text{Let } \vec{A} = \hat{i} + \hat{j}$$

$$\vec{B} = \hat{i} - \hat{j}$$

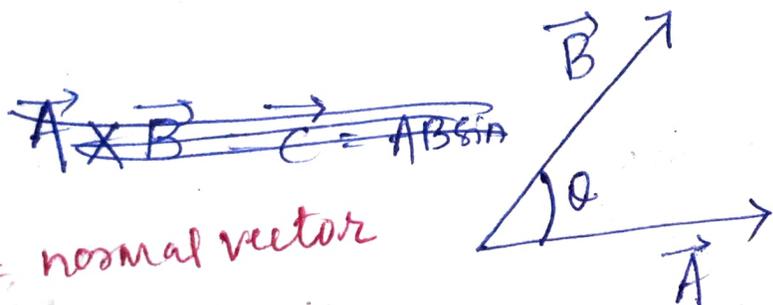
$$\vec{A} \cdot \vec{B} = 1 - 1 = 0$$

$$\boxed{\vec{A} \cdot \vec{B} = 0}$$

$$\therefore \vec{A} \perp \vec{B} \quad \theta = 90^\circ$$

$$= 5 - \frac{1}{2} = \frac{9}{2} = 4.5$$

Cross product / vector product



\hat{n} = normal vector

$$\vec{A} \times \vec{B} = \vec{C} = \underbrace{(AB \sin \theta)}_{\text{Magnitude}} \hat{n} \quad \text{— direction}$$

→ If we cross product two vector, we get the resultant as a vector quantity that have both magnitude and direction. Here (\vec{C}) is the resultant.

→ The direction of \hat{n} is perpendicular to the plane containing \vec{A} & \vec{B}

→ Direction of \hat{n} can be find by using right hand thumb rule.

$$(\vec{B} \times \vec{A}) = -\vec{c}$$

$$\therefore (\vec{B} \times \vec{A}) = -(\vec{A} \times \vec{B})$$

→ We should consider smaller angle between two vectors

The cross product of two vectors is a vector quantity whose magnitude is equal to product of magnitude of two vectors and sine of smaller angle in between them and its direction is always perpendicular to its plane.

$$(\vec{A} \times \vec{B}) = \vec{c} = AB \sin \theta \hat{n}$$


EX Torque (\vec{c}) = $\vec{r} \times \vec{F}$

Properties ✓

① $(\vec{A} \times \vec{B}) \neq (\vec{B} \times \vec{A})$

$\therefore (\vec{A} \times \vec{B}) = -(\vec{B} \times \vec{A})$

② $\vec{A} \times (\vec{B} + \vec{C}) = (\vec{A} \times \vec{B}) + (\vec{A} \times \vec{C})$

Characteristics of cross product:

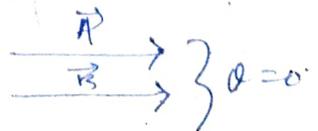
① colinear vector

② Parallel vector ($\theta = 0^\circ$)

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n}$$

$$= AB \sin 0^\circ$$

$$\vec{A} \times \vec{B} = \vec{0}$$



e.g

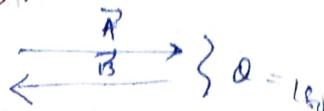
$$\hat{i} \times \hat{i} = 0$$

$$\hat{j} \times \hat{j} = 0$$

$$\hat{k} \times \hat{k} = 0$$

(b) Antiparallel vector ; - ($\theta = 180^\circ$)

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n}$$



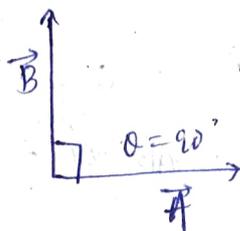
$$\Rightarrow \boxed{\vec{A} \times \vec{B} = \vec{0}}$$
 at θ is the condition for colinearity.

The cross product of two colinear vectors is always a zero vector. This condition is known as condition for colinearity.

Perpendicular vector

$$(\vec{A} \times \vec{B}) = AB \sin \theta \hat{n}$$

$$\Rightarrow \boxed{\vec{A} \times \vec{B} = AB \hat{n}}$$



ex $\hat{i} \times \hat{j} = |\hat{i}| \hat{n} = \hat{k}$

$$\hat{j} \times \hat{k} = \hat{i}$$

$$\hat{k} \times \hat{i} = (1)(1) \hat{n} = \hat{j}$$

$$\hat{j} \times \hat{k} = \hat{i}$$

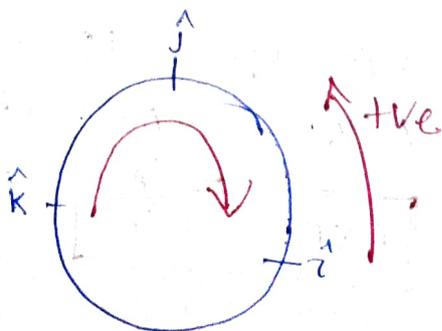
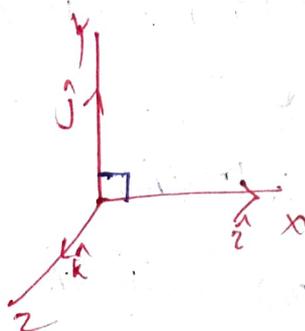
$$\hat{k} \times \hat{i} = (1)(1) \hat{n} = \hat{j}$$

$$\hat{k} \times \hat{j} = -\hat{i}$$

$$\Rightarrow \hat{j} \times \hat{i} = -\hat{k}$$

$$\Rightarrow \hat{k} \times \hat{j} = -\hat{i}$$

$$\hat{i} \times \hat{k} = -\hat{j}$$



Vector in three dimension / Three dimensional vector

$$\text{Let } \vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \overset{(+)}{\hat{i}} & \overset{(-)}{\hat{j}} & \overset{(+)}{\hat{k}} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$= +\hat{i} \begin{vmatrix} A_y & A_z \\ B_y & B_z \end{vmatrix} - \hat{j} \begin{vmatrix} A_x & A_z \\ B_x & B_z \end{vmatrix} + \hat{k} \begin{vmatrix} A_x & A_y \\ B_x & B_y \end{vmatrix}$$

$$= \hat{i}(A_y B_z - A_z B_y) - \hat{j}(A_x B_z - A_z B_x) + \hat{k}(A_x B_y - A_y B_x)$$

e.g

$$\vec{A} = 3\hat{i} + 2\hat{j} + 4\hat{k}$$

$$\vec{B} = 2\hat{i} + 3\hat{j} + 3\hat{k}$$

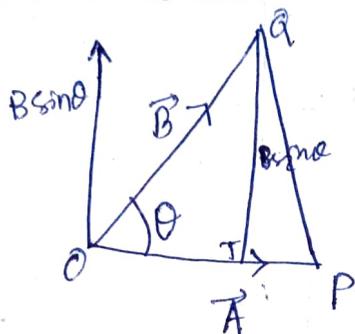
$$\vec{A} \times \vec{B} = \hat{i}(6 - 12) - \hat{j}(9 - 8) + \hat{k}(9 - 4)$$

$$= -6\hat{i} - \hat{j} + 5\hat{k}$$

Application of cross product

→ By the help of cross product we can find out the area of parallelogram, triangle.

Area of triangle :-



$$(\vec{A} \times \vec{B}) = AB \sin \theta \hat{n}$$

$$|\vec{A} \times \vec{B}| = AB \sin \theta$$

Area of the triangle
 $= \frac{1}{2} \times \text{base} \times \text{height}$

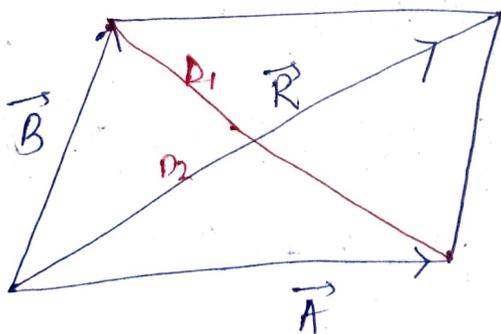
$$= \frac{1}{2} \times OP \times QT$$

$$= \frac{1}{2} A \times B \sin \theta$$

$$= \frac{1}{2} AB \sin \theta$$

$$= \frac{1}{2} |\vec{A} \times \vec{B}|$$

Area of parallelogram :-



→ Parallelogram made of two ~~vectors~~ triangles of
Area of one (1) triangle $= \frac{1}{2} |\vec{A} \times \vec{B}|$ then

$$\text{Area of parallelogram} = |\vec{A} \times \vec{B}| = 2 \times \frac{1}{2} |\vec{A} \times \vec{B}|$$

$$= |\vec{A} \times \vec{B}|$$

When diagonal is given then the

$$\text{Area of Parallelogram} = |\vec{B}_1 \times \vec{B}_2|$$

Problems on cross product

Q1 Let $\vec{A} = 2\hat{i} + 3\hat{j} - 4\hat{k}$
 $\vec{B} = 3\hat{i} - 2\hat{j} + 6\hat{k}$

if $\vec{C} = (\vec{A} \times \vec{B})$ then find direction.

Solⁿ

$$\vec{A} = 2\hat{i} + 3\hat{j} - 4\hat{k}$$

$$\vec{B} = 3\hat{i} - 2\hat{j} + 6\hat{k}$$

$$\begin{aligned} (\vec{A} \times \vec{B}) = \vec{C} &= \hat{i}(18 - 8) - \hat{j}(12 + 12) + \hat{k}(-4 - 9) \\ &= 10\hat{i} - 24\hat{j} - 13\hat{k} \end{aligned}$$

$$\hat{C} = \frac{\vec{C}}{|\vec{C}|} = \frac{10\hat{i} - 24\hat{j} - 13\hat{k}}{\sqrt{100 + 576 + 169}}$$

Q2 Find the value of $(\vec{A} \times \vec{B}) \cdot \vec{A}$

Ans

$$(\vec{A} \times \vec{B}) \cdot \vec{A}$$

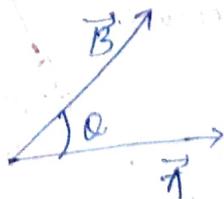
$$\text{Let } \vec{C} = (\vec{A} \times \vec{B})$$

$$\text{So } \vec{C} \cdot \vec{A} = CA \cos \theta$$

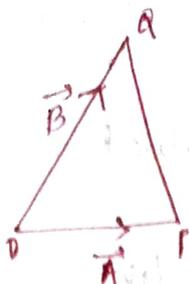
→ If we cross product $(\vec{A} \times \vec{B})$
we get \vec{C} then dirⁿ of \vec{C}
it is \perp to both \vec{A} and \vec{B} i.e.

$$\theta = 90^\circ \quad \vec{C} \cdot \vec{A} = CA \cos 90^\circ \quad (\because \theta = 90^\circ)$$

$$= 0$$



Q-2



here $\vec{A} = \hat{i} + \hat{j} + 3\hat{k}$

$\vec{B} = 2\hat{i} + 3\hat{j} - \hat{k}$

Find Area of triangle

Solⁿ

Area = $\frac{1}{2} |\vec{A} \times \vec{B}|$

$\vec{A} \times \vec{B} = \hat{i}(-1-9) - \hat{j}(-1-6) + \hat{k}(3-2)$

$\Rightarrow (\vec{A} \times \vec{B}) = -10\hat{i} + 7\hat{j} + \hat{k}$

$|\vec{A} \times \vec{B}| = \sqrt{100 + 49 + 1}$

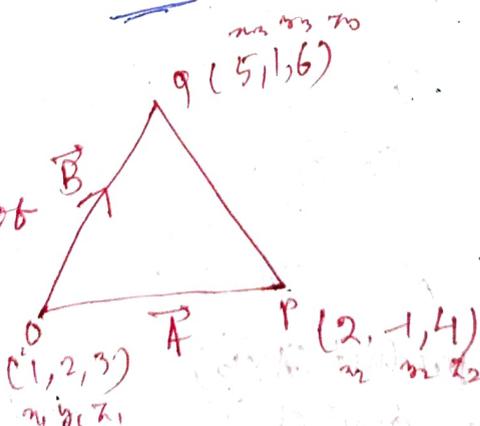
$= \sqrt{150}$

Area = $\frac{1}{2} \times \sqrt{150}$

Ans

Q4

Find Area of this vector.



$\vec{A} = (x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k}$

$\vec{B} = (x_3 - x_1)\hat{i} + (y_3 - y_1)\hat{j} + (z_3 - z_1)\hat{k}$

then Area = $\frac{1}{2} |\vec{A} \times \vec{B}|$

Find co-ordinate then cross product then

Questions on vector

96 $|\vec{A} \times \vec{B}| = r_3 (\vec{A} \cdot \vec{B})$
then find $|\vec{A} + \vec{B}|$

Solⁿ
 $|\vec{A} - \vec{B}| = \sqrt{A^2 + B^2 - 2AB \cos \theta}$

$$|\vec{A} \times \vec{B}| = r_3 (\vec{A} \cdot \vec{B})$$

$$\Rightarrow AB \sin \theta = r_3 AB \cos \theta$$

$$\Rightarrow \tan \theta = r_3$$

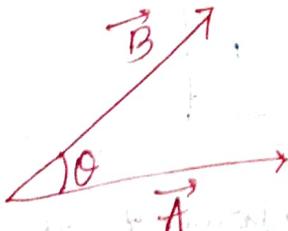
$$\Rightarrow \tan \theta = \tan 60^\circ$$

$$\Rightarrow \boxed{\theta = 60^\circ}$$

$$|\vec{A} - \vec{B}| = \sqrt{A^2 + B^2 - 2AB \cdot \frac{1}{2}}$$
$$= \sqrt{A^2 + B^2 - AB}$$

$$\left[\begin{array}{l} \therefore \theta = 60^\circ \\ \cos 60^\circ = \frac{1}{2} \end{array} \right]$$

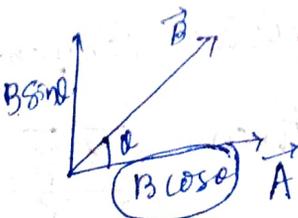
Note



1) Find scalar component of \vec{B} along \vec{A}

2) Find vector component of \vec{B} along \vec{A}

Solⁿ
1) Scalar component
 $= B \cos \theta$
 $= B \cdot \frac{1}{2}$



Let me resolve \vec{B}
then i will find two
component $B \cos \theta$ & $B \sin \theta$
where as $B \cos \theta$ along
 \vec{A} .

Scalar component

$$\begin{aligned} &= B \cos \theta \\ &= B \left(\frac{\vec{A} \cdot \vec{B}}{AB} \right) \\ &= \left(\frac{\vec{A} \cdot \vec{B}}{A} \right) \end{aligned}$$

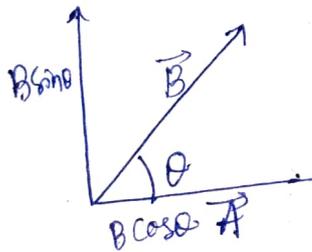
$$\left[\begin{aligned} \vec{A} \cdot \vec{B} &= AB \cos \theta \\ \frac{\vec{A} \cdot \vec{B}}{A \cdot B} &= \cos \theta \end{aligned} \right]$$

Formula for scalar component of \vec{B} along $\vec{A} = \frac{\vec{A} \cdot \vec{B}}{A}$

→ If it is ask find scalar component of \vec{A} along \vec{B} then

$$\frac{\vec{B} \cdot \vec{A}}{B}$$

②
Solⁿ



Though vector has both magnitude and direction so we have to find both dirⁿ & magnitude

Vector component of \vec{B} along \vec{A}

$$\begin{aligned} &= (B \cos \theta) \hat{A} \\ &= B \cdot \left(\frac{\vec{A} \cdot \vec{B}}{AB} \right) \hat{A} \end{aligned}$$

$$= \left(\frac{\vec{A} \cdot \vec{B}}{A} \right) \hat{A}$$

Question Find scalar component of \vec{x} along \vec{y}

$$= \frac{\vec{x} \cdot \vec{y}}{y}$$

If it is given vector component of \vec{x} along \vec{y}

then $\left(\frac{\vec{x} \cdot \vec{y}}{y} \right) \hat{y}$

① Find vector component \vec{P} along \vec{q}

$$= \left(\frac{\vec{P} \cdot \vec{q}}{q} \right) \hat{q}$$

Problem 1

$$\text{Let } \vec{A} = 2\hat{i} + 3\hat{j} - 4\hat{k}$$

$$\vec{B} = 3\hat{i} - \hat{j} - 4\hat{k}$$

Find a scalar component of \vec{A} along \vec{B}

$$\frac{\vec{A} \cdot \vec{B}}{B} =$$

$$\vec{A} \cdot \vec{B} = (2\hat{i} + 3\hat{j} - 4\hat{k}) \cdot (3\hat{i} - \hat{j} - 4\hat{k})$$

$$= \frac{6 - 3 + 16}{\sqrt{3^2 + 1^2 + 4^2}} = \frac{19}{\sqrt{26}}$$

② Find vector component of \vec{A} along \vec{B}

$$= \left(\frac{\vec{A} \cdot \vec{B}}{B} \right) \hat{B}$$

$$= \frac{19}{\sqrt{26}} \times \frac{\vec{B}}{B}$$

$$= \frac{19}{\sqrt{26}} \frac{3\hat{i} - \hat{j} - 4\hat{k}}{\sqrt{26}}$$

$$= \frac{19}{26} (3\hat{i} - \hat{j} - 4\hat{k})$$